

# ELMÉLETI FIZIKAI MÓDSZEREK A KÖRNYEZETTUDOMÁNYBAN

## 5. gyakorlat

- $\mathbf{a} = (a_1, a_2, a_3)$ ,  $\mathbf{b} = (b_1, b_2, b_3)$ ,  $\mathbf{v} = (v_1(x, y, z), v_2(x, y, z), v_3(x, y, z))$   
 $\mathbf{r} = (x, y, z)$  vagy  $\mathbf{r} = (x_1, x_2, x_3)$  és  $r = \sqrt{x^2 + y^2 + z^2}$   
 $\varphi(x, y, z)$  skalár

- vektor-skalár fv.:  $\varphi(\mathbf{r}) = \varphi(x, y, z) = xy \sin z + e^{\sqrt{xy}}$   
vektor-vektor fv.:  $\mathbf{v}(\mathbf{r}) = \mathbf{v}(x, y, z) = (x^y, \cos(xy), -y \sin z^3) = x^y \mathbf{i} + \cos(xy) \mathbf{j} + (-y \sin z^3) \mathbf{k}$

- skalárszorzat:  $\mathbf{a} \cdot \mathbf{b} = a_1 b_1 + a_2 b_2 + a_3 b_3 = \sum_{i=1}^3 a_i b_i$   
vektoriális szorzat:

$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \begin{pmatrix} a_2 b_3 - a_3 b_2 \\ a_3 b_1 - a_1 b_3 \\ a_1 b_2 - a_2 b_1 \end{pmatrix}$$

- differenciáloperátorok:  $\nabla = \left( \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) = \left( \frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_3} \right) = (\partial_1, \partial_2, \partial_3)$

gradiens:  $\text{grad} \varphi = \nabla \varphi = \left( \frac{\partial \varphi}{\partial x}, \frac{\partial \varphi}{\partial y}, \frac{\partial \varphi}{\partial z} \right) = \left( \frac{\partial \varphi}{\partial x_1}, \frac{\partial \varphi}{\partial x_2}, \frac{\partial \varphi}{\partial x_3} \right) = (\partial_1 \varphi, \partial_2 \varphi, \partial_3 \varphi)$   
 $(\text{grad} \varphi)_i = \partial_i \varphi$

divergencia:  $\text{div} \mathbf{v} = \nabla \cdot \mathbf{v} = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z} = \sum \frac{\partial v_i}{\partial x_i} = \sum \partial_i v_i$   
 $\text{div} \mathbf{v} = \sum \partial_i v_i$

rotáció:  $\text{rot} \mathbf{v} = \nabla \times \mathbf{v} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \partial_1 & \partial_2 & \partial_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = \begin{pmatrix} \partial_2 v_3 - \partial_3 v_2 \\ \partial_3 v_1 - \partial_1 v_3 \\ \partial_1 v_2 - \partial_2 v_1 \end{pmatrix} = \begin{pmatrix} \frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \\ \frac{\partial v_1}{\partial z} - \frac{\partial v_3}{\partial x} \\ \frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \end{pmatrix}$

$$(\text{rot} \mathbf{v})_i = \sum_{j,k} \varepsilon_{ijk} \partial_j v_k$$

$$\varepsilon_{ijk} = \begin{cases} 1 & , \text{ ha } ijk = 123, 231, 312 \\ -1 & , \text{ ha } ijk = 132, 213, 321 \\ 0 & , \text{ ha legalább 2 megegyezik közülük} \end{cases}$$

Laplace-operátor:  $\Delta \equiv \nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} = \frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{\partial^2}{\partial x_3^2} = \sum \partial_i^2$

1.  $\mathbf{v} = (2^{-x+y}, 8^{-y+z}, 4^{x-z})$ ,  $\text{div} \mathbf{v} = ?$ ,  $\text{rot} \mathbf{v} = ?$
2.  $\text{grad} r^3 = ?$
3.  $\text{rot} \text{grad} r^3 = ?$
4.  $\text{div} \text{grad} r^3 = ?$
5.  $\mathbf{v} = \left( -\frac{y}{r^3}, \frac{x}{r^3}, 0 \right)$ ,  $\text{div} \mathbf{v} = ?$
6.  $\mathbf{v} = (cx, cy, 0)$ ,  $\text{div} \mathbf{v} = ?$ ,  $\text{rot} \mathbf{v} = ?$
7.  $\mathbf{v} = (c(x^2 + y^2), c(x^2 + y^2), 0)$ ,  $\text{div} \mathbf{v} = ?$ ,  $\text{rot} \mathbf{v} = ?$
8.  $\mathbf{v} = (x^2 y z^3, y^2 z, x^2 z)$ ,  $\text{div} \mathbf{v} = ?$ ,  $\text{rot} \mathbf{v} = ?$
9.  $\mathbf{v} = \left( \frac{x}{r^3}, \frac{y}{r^3}, \frac{z}{r^3} \right)$ ,  $\text{div} \mathbf{v} = ?$
10.  $\mathbf{v} = (x r^3, y r^3, z r^3)$ ,  $\text{div} \mathbf{v} = ?$ ,  $\text{rot} \mathbf{v} = ?$

11.  $\mathbf{v} = c \frac{\mathbf{r}}{r^2}$ ,  $\operatorname{div} \mathbf{v} = ?$ ,  $\operatorname{rot} \mathbf{v} = ?$

12.  $\mathbf{v} = (r, r^2, r^3)$ ,  $\operatorname{div} \mathbf{v} = ?$ ,  $\operatorname{rot} \mathbf{v} = ?$

13.  $\mathbf{v} = \mathbf{r} e^r$ ,  $\operatorname{div} \mathbf{v} = ?$ ,  $\operatorname{rot} \mathbf{v} = ?$